Garuda Robotics Plex Pilot GCS Quick Start Guide



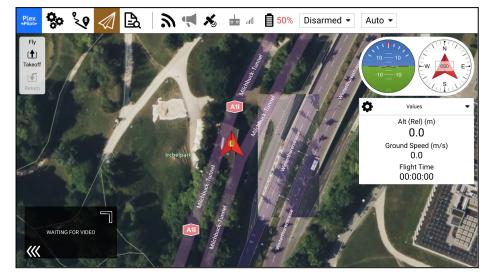
Guide version:1.0Guide revision:2023-10-02



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Fly View

The Fly view is the default screen upon launching Plex Pilot.

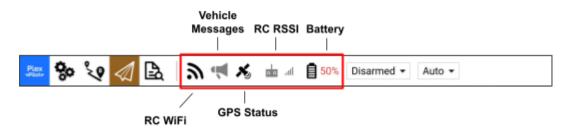


Settings Setup Plan Fly Analyze



The main toolbar consists of 5 tabs:

- Settings: Configure the Plex Pilot application.
- Setup: Configure and tune the connected UA.
- Plan: Create autonomous missions and geofences.
- Fly: Monitor the UA while flying.
- Analyze: View and download flight logs.



There are 5 main status icons::

- **RC WiFi:** Status of RC connection to drone WiFi AP.
- Vehicle Messages: Shows list of messages from UA (check for error messages).
- GPS Status: Shows satellite count and current HDOP.
- **RC RSSI:** RC signal strength information.
- Battery: Remaining battery percent of UA.

Settings View

The Settings View is used to configure the settings for the Plex Pilot application. Click on the Plex Pilot logo (top left) to access the Settings View.

Plex Pilote	V 🕼 🖻			Waiting For Vehicle Connection
General	Units			
Comm Links		Distance	Meters	-
Offline Maps		Area	SquareMeters	•
MAVLink		Speed	Meters/second	-
Console		Temperature	Celsius	•
Help	Miscellaneous			
		Language	System	•
		Color Scheme	Outdoor	•
		Map Provider	Bing	•
		Мар Туре	Hybrid	•

Configurable settings

Section	Description
General	UI preferences, Device auto connection, RTK GPS, Video Stream etc.
Comm Links	Manually create communication links
Offline Maps	Download maps for offline use
MAVLink	MAVLink and autopilot specific settings
Console	Capture application logs for diagnosing application problems

Setup View

The Setup View is used to configure a vehicle before flight.

Click on the 😵 icon (second from top left) to access the Setup View.

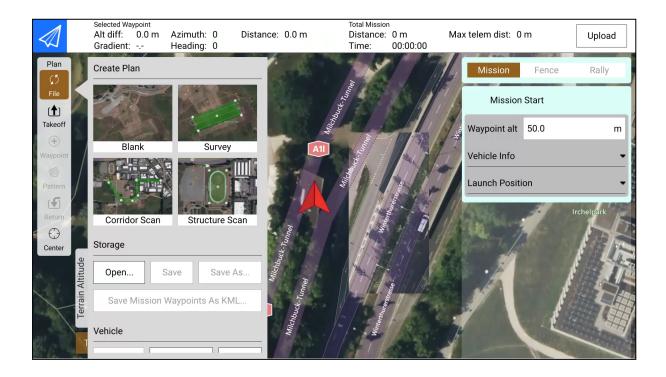
Plex Spilot=	گ €ي	F 🛛	(50%	Disarmed 🗸	Unknown	•
Below you will find a summary of the settings for your vehicle. To the left are the setup menus for each component Summary						each component.		
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			Radio	٠			Flight Modes	٠
Radio	Roll Pitch			Channel 1 Channel 2	F	Flight Mode 1 Flight Mode 2		Auto RTL
N Flight	Yaw Throttl Modes	le		Channel 4 Channel 3	F	Flight Mode 3 Flight Mode 4 Flight Mode 5 Flight Mode 6		Loiter FBWA STABILIZE Manual
((o)) Senso	rs							
Power			Sensors	•			Power	
Motor	Compa Compa S Compa	ass 2	Sec	Primary, External condary, Internal	В	Batt1 monitor Batt1 capacity Batt2 monitor	Analog	Voltage and Current 3300 mAh Disabled

Summary

An overview of all the important setup options for your vehicle. A summary block is marked with a red indicator if there are still settings needed to be adjusted/specified, and green if ready. You should not fly If any of these indicators are red.

Plan View

The *Plan View* is used to plan and upload autonomous missions to your vehicle. Click on the **V** icon (third from top left) to access the *Plan View*.



Analyze View

The Analyze View provides tools to retrieve and display data from the vehicle. Click on the icon (fifth from top left) to access the Analyze View.

Plex 🌮 🍾 🖉	F 🛛 🐨	🕻 🔏 📥 .iil 📋 50%	Disarmed 👻	Unknown -	
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MAVLink Console	120/31/2	10/10/20 0.10 AM	00	rending	Download
					Erase All
MAVLink Inspector					Cancel

Log Download

List, download and clear logs on the vehicle.

MAVLink Console

Access the NSH shell running on the vehicle.

MAVLink Inspector

Display and chart received MAVLink messages/values.

Operating the drone

failsafe

Setting up UA internet connection

- 1. Purchase a 5G SIM Card.
- 2. Insert into a mobile device to verify the SIM card is able to access the internet.
- 3. Remove and insert the SIM Card into the drone (refer to the drone's User Manual).
- 4. Ensure that the drone is powered and connected to Plex Pilot.
- Under Setup View > Modem > APN Configuration, enter your SIM card's APN. Refer to your telco provider website if you are unsure what your APN is.
- 6. Once done click save. To verify internet connectivity, scroll down to *Latency Test* and click on *Test*. Wait for the latency test to complete. The test results should display a green/orange/red indicator.

Green - Good connectivity

Orange - Poor connectivity

Red - No connectivity

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((c)) Sensors	US8 Interface	/dev/ttyUS82		
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Motors	Username			
Safety	Password Network Mode	AUTO -		
	Data Period	WEEKLY •		
Modern	Data Limit (MB)	0 2 Save		
Parameters				
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Late	ency Test			
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Safety	Wait Duration			
↑ 👌 🕴 Tuning	Packet count: 10 Packet loss: 0	3 Test		
🍋 Modem				
Parameters	and age to only			

Troubleshooting

Maintenance

[upgrades]